# Department of Mathematics Faculty of Mathematics & Computer Science M.Sc. (Applied Mathematics), 3<sup>rd</sup> Semester

| Course              | AM 304(d)         |
|---------------------|-------------------|
| Code                |                   |
| <b>Course Title</b> | Dynamical Systems |
| Course              | 04                |
| Credits             |                   |

### **Course objectives:**

Learn and use various tools for the analysis and control of nonlinear systems. Know and play with a wide variety of interesting, inherently nonlinear examples. Learn how to study complexity of nonlinear systems.

### Minimum pre-requisites:

AM 102: Numerical Analysis & Methods AM 103: Ordinary Differential Equations & Applications AM 202: Numerics of Ordinary Differential Equations

## **Course structure:**

Linear dynamical systems: Introduction and preparatory material, linear versus nonlinear systems, equilibria, diagonalization, Jordan canonical form, stability, stable, unstable, and center subspaces, non-homogeneous systems; Solutions of nonlinear dynamical systems: Preliminary concepts, solutions of initial value problems, existence and uniqueness of solutions, continuous dependence on initial conditions and parameters, Linearization methods flows. classical examples. for nonlinear dynamical systems: Linearization, invariant manifolds, stable, unstable and center manifolds, Hartman-Grobman theorem; Lyapunov stability theory for nonlinear dynamical systems: Lyapunov functions, Lie derivative, stability and instability theorems, LaSalle Invariance Principle, exponential stability; Global theory of nonlinear dynamical systems: Periodic orbits, limit cycles, attractors, Poincar'e-Bendixon theorem, Poincar'e maps, index theory, examples: harmonic oscillator, Duffing's equation, and Lotka-Volterra predator-prey model; Bifurcation theory for nonlinear dynamical systems: Bifurcations of vector fields, saddle-node,

transcritical, pitchfork and Hopf bifurcations, codimension of a bifurcation, stability under perturbations, structural stability, Euler's buckling beam and van der Pol oscillator.

# **Reading Suggestions:**

- Differential Equations and Dynamical Systems, 3rd Edition, 2006, L Perko.
- Differential Dynamical Systems, 2007, James Meiss, SIAM.
- Dynamical Systems with Applications using Maple 2nd Ed, 2010, Stephen Lynch, Springer.
- Introduction to Applied Nonlinear Dynamical Systems and Chaos, 2003, Stephen Wiggins, Texts in Applied Mathematics, Springer.

# **Evaluation and weightage:**

| • | Com | pute | r As | ssigni | ment 1 | :10%    |
|---|-----|------|------|--------|--------|---------|
|   | ~   |      |      |        |        | 4 0 0 / |

- Computer Assignment 2 :10%
  Lab :10%
- Lab :10%
   Mid Term Exam :30%
   End Term Exam :40%